

WHAT IS CLAIMED IS:

1 *Sub A1* 1. A system for repositioning teeth from an
 2 initial tooth arrangement to a final tooth arrangement, said
 3 system comprising a plurality of dental incremental position
 4 adjustment appliances including:
 5 a first appliance having a geometry selected to
 6 reposition the teeth from the initial tooth arrangement to a
 7 first intermediate arrangement;
 8 one or more intermediate appliances having
 9 geometries selected to progressively reposition the teeth from
 10 the first intermediate arrangement to successive intermediate
 11 arrangements; and
 12 a final appliance having a geometry selected to
 13 progressively reposition the teeth from the last intermediate
 14 arrangement to the final tooth arrangement.

1 2. A system as in claim 1, wherein the appliances
 2 comprise polymeric shells having cavities shaped to receive
 3 and resiliently reposition teeth from one arrangement to a
 4 successive arrangement.

1 *Sub A2* 3. A system as in claim 2, wherein the tooth
 2 positions defined by the cavities in each successive appliance
 3 differ from those defined by the prior appliance by no more
 4 than 2 mm.

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 2 4. A system as in claim 1, comprising at least two
 3 intermediate appliances.

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 2 5. A system as in claim 4, comprising at least ten
 3 intermediate appliances.

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 2 6. A system as in claim 5, comprising at least
 3 twenty-five intermediate appliances.

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7. A method for repositioning teeth from an initial tooth arrangement to a final tooth arrangement, said method comprising:

placing a first incremental position adjustment appliance in a patient's mouth, wherein the first appliance has a geometry selected to reposition the teeth from the initial tooth arrangement to a first intermediate arrangement;

successively replacing one or more additional appliances, wherein the additional appliances have geometries selected to progressively reposition the teeth from the first intermediate arrangement to successive intermediate arrangements; and

placing a final appliance into the patient's mouth, wherein the final appliance has a geometry selected to progressively reposition the teeth from the last intermediate arrangement to the final tooth arrangement.

8. A method as in claim 7, wherein the appliances comprise polymeric shells having cavities shaped to receive and resiliently reposition teeth from one arrangement to a successive arrangement.

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9. A method as in claim 8, where the tooth positions defined by the cavities in each successive appliance differ from those defined by the prior appliance by no more than 2 mm.

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10. A method as in claim 7, wherein the successively placing step comprises placing at least two additional appliances prior to placing the final appliance.

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11. A method as in claim 10, wherein the successively placing step comprises placing at least ten additional appliances.

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12. A method as in claim 11, wherein the successively placing step comprises placing at least twenty-five additional appliances.

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~~13.~~ A method as in claim ~~7~~⁶, wherein the appliances
 are successively replaced at an interval in the range from
 2 days to 20 days.

Sub A5
 14. An improved method for repositioning teeth
 using appliances comprising polymeric shells having cavities
 shaped to receive and resiliently reposition teeth to produce
 a final tooth arrangement, wherein the improvement comprises
 determining at the outset of treatment geometries for at least
 three appliances which are to be worn successively by a
 patient to reposition teeth from an initial tooth arrangement
 to the final tooth arrangement.

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~~15.~~ An improved method as in claim ~~14~~¹², wherein at
 least four geometries determined at the outset.

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~~16.~~ An improved method as in claim ~~15~~¹³, wherein at
 least ten geometries are determined at the outset.

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~~17.~~ An improved method as in claim ~~16~~¹⁴, wherein at
 least twenty-five geometries are determined at the outset.

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 18. An improved method as in claim 14, wherein the
 tooth positions defined by the cavities in each successive
 geometry differ from those defined by the geometry by no more
 than 2 mm.

19. A method for producing a digital data set
 representing a final tooth arrangement, said method
 comprising:
 providing an initial digital data set representing
 an initial tooth arrangement;
 presenting a visual image based on the initial data
 set;

8 manipulating the visual image to reposition
9 individual teeth in the visual image; and
10 producing a final digital data set representing the
11 final tooth arrangement with repositioned teeth as observed in
12 the image.

1 20. A method as in claim 19, wherein the step of
2 providing a digital data set representing an initial tooth
3 arrangement comprises scanning a three-dimensional model of a
4 patient's teeth.

1 21. A method as in claim 20, wherein the
2 manipulating step comprises:
3 defining boundaries about at least some of the
4 individual teeth; and
5 moving at least some of the tooth boundaries
6 relative to the other teeth in an image based on the digital
7 data set.

1 22. A method for producing a plurality of digital
2 data sets representing a series of discrete tooth arrangements
3 progressing from an initial to a final arrangement, said
4 method comprising:
5 providing a digital data set representing an initial
6 tooth arrangement;
7 providing a digital data set representing a final
8 tooth arrangement;
9 producing a plurality of successive digital data
10 sets based on the provided digital data sets, wherein said
11 plurality of digital data sets represent a series of
12 successive tooth arrangements progressing from the initial
13 tooth arrangement to the final tooth arrangement.

1 23. A method as in claim 22, wherein the step of
2 providing a digital data set representing an initial tooth
3 arrangement comprises scanning a three-dimensional model of a
4 patient's teeth.

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1 24. A method as in claim 22, wherein the step of
2 providing a digital data set representing a final tooth
3 arrangement comprises:

4 defining boundaries about at least some of the
5 individual teeth; and

6 moving at least some of the tooth boundaries
7 relative to the other teeth in an image based on the digital
8 data set to produce the final data set.

1 25. A method as in claim 22, wherein the step of
2 producing a plurality of successive digital data sets
3 comprises determining positional differences between the
4 initial data set and the final data set and interpolating said
5 differences.

1 26. A method as in claim 25, wherein the
2 interpolating step comprises linear interpolation.

1 27. A method as in claim 25, wherein the
2 interpolating step comprises non-linear interpolation.

1 28. A method as in claim 25, further comprising
2 defining one or more key frames between the initial tooth
3 arrangement and final tooth arrangement and interpolating
4 between the key frames.

1 29. A method for fabricating a plurality of dental
2 incremental position adjustment appliances, said method
3 comprising:

4 providing a digital data set representing an initial
5 tooth arrangement;

6 providing a digital data set representing a final
7 tooth arrangement;

8 producing a plurality of successive digital data
9 sets based on the provided digital data sets, wherein said
10 plurality of digital data sets represent a series of

11 successive tooth arrangements progressing from the initial
12 tooth arrangement to the final tooth arrangement; and
13 fabricating appliances based on at least some of the
14 produced digital data sets.

1 30. A method as in claim 29, wherein the step of
2 providing a digital data set representing an initial tooth
3 arrangement comprises scanning a three-dimensional model of a
4 patient's teeth.

1 31. A method as in claim 29, wherein the step of
2 providing a digital data set representing a final tooth
3 arrangement comprises:
4 defining boundaries about at least some of the
5 individual teeth; and
6 moving at least some of the tooth boundaries
7 relative to the other teeth in an image based on the digital
8 data set to produce the final data set.

1 32. A method as in claim 29, wherein the step of
2 producing a plurality of successive digital data sets
3 comprises determining positional differences between the
4 initial data set and the final data set and interpolating said
5 differences.

1 33. A method as in claim 32, wherein the
2 interpolating step comprises linear interpolation.

1 34. A method as in claim 32, wherein the
2 interpolating step comprises non-linear interpolation.

1 35. A method as in claim 32, further comprising
2 defining one or more key frames between the initial tooth
3 arrangement and final tooth arrangement and interpolating
4 between the key frames.

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43. A method as in claim 42, wherein the controlling step comprises selectively hardening a non-hardened resin to produce the appliance and separating the appliance from the remaining liquid resin.

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